# **3701/44 ADAPT Aeroderivative Monitor** Datasheet

Bently Nevada Machinery Condition Monitoring

100M8649 Rev. R



3701/44 Simplex



3701/44 Duplex

## Advanced Distributed Architecture Platform Technology - ADAPT

The Bently Nevada Advanced Distributed Architecture Platform Technology, or ADAPT 3701, is a family of compact, high performance safety and machinery protection and condition monitoring solutions. ADAPT products are targeted at specific assets and applications, and excel at the intensive signal processing necessary to identify early indicators of machine failure modes long before an alarm.

## Description

The 3701/44 ADAPT Aero Monitor is specifically designed for protection and condition monitoring on aeroderivative gas turbines and their driven equipment. The 3701/44 is optimized for the signal processing required on aero gas turbines such as 1X order tracking of casing vibration at multiple rotor speeds, narrow band high order filtering, multiple bandpass filters on a single sensor and combustion dynamic pressure pulsation measurement. The 3701/44 with dual redundant (DR) processor modules is designed for protection on critical rotating machinery.

The 3701/44 has a rugged industrial design allowing it to be skid mounted close to the machine and reduce installation wiring. Its compact small size provides more mounting options compared to traditional rack based solutions. It is capable of accepting a wide array of sensor types, including eddy current proximity probes, charge-coupled accelerometers, Integrated Circuit Piezoelectric Sensors (IEPE), velocity, acceleration, dynamic pressure, and magnetic speed pick-ups.

ADAPT 3701 is configured and validated with Bently Nevada Monitor Configuration (BNMC) software. BNMC is a simple and powerful configuration and validation environment used for the 3701/44 Aero Monitor. It is ordered separately and is required for operation.





The 3701/44 Aeroderivative Monitor is a selfcontained device that is ordered with a single part number for either a simplex or duplex terminal base and is made up of these major components:

Part	Quantity Required in Each 3701/44
3701 Simplex Terminal Base	1
3701 Processor Module	1
3701 Input Module	1 or 2
3701 Output Module	lornone

Part	Quantity Required in Each 3701/44
3701 Duplex Terminal Base	1
3701 Processor Module	2
3701 Input Module	1 or 2
3701 Output Module	lornone

## 3701/44 Overview

The 3701/44 is a robust, compact, selfcontained 12-channel device with sophisticated signal processing capability and with a form-factor suitable for distribution close to machinery. The ADAPT Aero has a modular construction that allows field changing of components and is fully-configurable. It combines protection and condition monitoring (CM) in a single package. With the ability to define measurements and alarms within the monitor itself, it can act as a stand-alone protection and CM system. There is no need for any interaction with external software to trigger or control the monitor during operation. The 3701/44 DR Machinery Dynamics Monitor is a compact, field mountable, vibration protection system that utilizes dual redundant processor modules.

In the DR version, each processor module is identically configured and redundantly digitizes and processes all sensor inputs, executes identical logic, and each processor module independently drives separate alarm relays.

#### **3701 Digital Communications**

The 3701/44 has two independent Ethernet physical RJ45 connections per CPU for digital communication with Bently Nevada software products hosted on network computers and plant automation systems. It uses a proprietary Ethernet protocol for communicating with System\_1\_Evolution software and the BNMC configuration software.

The 3701/44 includes two Ethernet ports per CPU which provide Ethernet TCP/IP communications capabilities. Standard industrial protocols are:

Modbus TCP/IP

Modbus over Ethernet is available for connection to HMI's, unit control systems, or other plant automation equipment. The 3701 can only be configured as a server.

• Ethernet Global Data (EGD)

EGD is a GE protocol used on Mark VI and Mark Vie controllers and by GE Programmable Automation Controllers and certain 3<sup>rd</sup> party automation equipment.

#### 3701/44 System Description

The 3701/44 monitor is powered by single or dual redundant external +24 Vdc power. It consists of four main physical component; the terminal base (single or dual), one ot two processor modules, one or two input modules, and an output module.

The terminal base is the mounting platform for the monitor. The different modules install into the terminal base and two pluggable field wiring termination blocks plug into the terminal base. Sensor wiring terminates on the wiring blocks and terminations for discrete inputs



(Reset, Trip Multiply, etc.) terminate directly on the base but on the opposite side from sensor wiring.

The processor module is the monitor's CPU. It is the center of the logic and signal processing for the monitor.

There are two terminal base configurations:

- A simplex base, which contains 1 CPU processor card
- A duplex base which contains 2 CPU processor cards.

The use of 2 processor cards allows for redundancy for all the dynamic measurements; both processors have access to all signal channels from each input module.

The input modules are the interface to the sensors. Each input module type covers multiple sensor varieties but due to the number of sensor types there are different input modules. The input modules condition the analog sensor signals for delivery to A/D conversion on the processor module. The input modules are simple, reliable, analog circuitry but with a simple microcontroller (outside the protection path) to provide diagnostics and fault detection on each module. Buffered transducer outputs are provided at a multi-pin Dsub connector on each input module. An accessory cable is available to fan the buffered outs to BNC or ADRE 408 Dspi compatible connectors.

The output modules are for monitor outputs such as relay contacts or 4- 20 mA analog outputs. At the current time only the 8-Channel Relay Output Module is available. It contains 8 programmable SPDT relays and a dedicated monitor Protection Fault (OK) Relay. Relay logic is created in the BNMC software using the graphical logic editor.

#### **Processor Module**

The processor module, or CPU module, performs A/D conversion, digital signal processing, alarm and logic processing, and communications to Bently Nevada software and plant automation systems. The CPU module employs sophisticated diagnostics and fault detection processing to enhance reliability, availability, and maintainability of the protection and monitoring system.

## **Input Modules**

#### 3701 Proximitor Accelerometer Aeroderivative (PAA) Input Module

The 3701 PAA input module is a 6-channel + Keyphasor/speed input module that interfaces to a variety of sensors such as: -24 Volt Proximitor sensors, -24 Volt 3-wire Accelerometers, Charge-Amplifiers, and differential output Aeroderivative Interface Modules used with charge-coupled hi-temp accelerometers or dynamic pressure sensors.

Any of the PAA's six channels (1 – 6) can be independently configured for one of the supported transducers. Each PAA supports one dedicated Keyphasor or speed measurement on channel 7 that is configurable for Proximitor sensors or magnetic pick-ups. A 2-wire, galvanically isolated, hi-impedance input is available for magnetic pick-up speed sensors. The isolated input eliminates potential ground loops that can occur when speed sensors are shared between the vibration system and other instrumentation.

#### 3701 Proximitor Accelerometer Velomitor (PAV) Input Module

The 3701 PAV input module is a 6-channel + Keyphasor/speed input module that interfaces to a variety of sensors such as: -24 Volt Proximitor sensors, -24 Volt 3-wire Accelerometers, Velomitor sensors, and constant current 2-wire sensors that are compatible with the -24 Volt 2-wire Velomitor interface.

Any of the PAV's six channels (1–6) can be independently configured for one of the supported transducers. Each PAV supports one dedicated Keyphasor or speed measurement on channel 7 that is configurable for Proximitor sensors or magnetic pick-ups.

### 3701 Positive (PoV) Input Module



The 3701 PoV input module is a 6-channel + Keyphasor/speed input module that interfaces to a variety of positively powered sensors such as: +24 V Proximitor sensors, +24 V Interface modules, and 2 wire IEPE sensors using 3.3 mA constant current.

Any of the PoV's six channels (1-6) can be independently configured for one of the supported transducers. Each PoV supports one dedicated negatively powered Keyphasor or speed measurement on channel 7 that is configurable for Proximitor sensors or magnetic pick-ups.



### **Output Modules**

#### 3701 8-Channel Relay Output Module

The 3701 8-Ch Relay Output Module provides 8 SPDT relay outputs or 4 "virtual" DPDT outputs and a dedicated Protection Fault relay. Relay logic is user programmable in the BNMC software using the graphical logic editor. The processor module operates on the relay logic to drive relay state.

The Protection Fault relay is a normally energized SPDT relay that will de-energize on fault conditions that can compromise the monitor's availability to protect machinery. The protection fault relay is similar to a traditional OK relay but certain conditions that do not compromise protection will not cause the Protection Fault relay to de-energize.

The relays are configured for Normally De-Energized (NDE) or Normally Energized (NE) in four banks of two relays each using a switch on the relay module.

Relay wiring terminates on the output module using pluggable connectors and exits on the opposite side of the monitor from the sensor inputs.

In dual redundant operation, processor module one drives relays 1, 3, 5, and 7 and processor module two drives relays 2, 4, 6, and 8. The relay alarm logic is identical. External connection to an Emergency Shutdown Device can use a loo2 or 2002 configuration depending on the user's needs. Users are recommended to perform a system analysis using functional safety methods (IEC 61511, IEC 61508 or ISA SP84) before selecting a voting scheme.

## **Terminal Base**

## 3701 Simplex and Duplex Terminal Bases

The term "simplex terminal base" identifies, or distinguishes this type of terminal base as one with a single (simplex) processor module as opposed to a dual (or duplex) terminal base with two processor modules.

The 3701 simplex terminal base is the mounting and installation component of the monitor. It supports a single processor module, one or two input modules, and an output module.

The terminal base mounts to a bulkhead, or enclosure or wall sub-panel using the four mounting holes at the corners of the base. Mount vertically for optimal convection cooling.

The duplex terminal base is similar in function to the simplex terminal base except that it has two CPU processor modules instead of one. The extra CPU module allows the user to use the two input modules redundantly. Both CPU modules have access to all the signal channels from each of the input modules.

Terminal base features:

- Two pluggable terminal blocks provide sensor wiring terminations that are individually marked for the sensor wire type. The termination blocks can be removed for wiring ease or maintenance work and, when installed, are fixed in place with a locking mechanism.
- A dedicated connection terminal for single point connection to system earth.
- A single point earth connection switch to separate physical (chassis) earth from system common (instrument earth) to enable system common connection to an external intrinsic safety earth.
- Primary and secondary connectors for single or redundant +24 V DC power input.
- Six discrete inputs (DI) for dedicated dry contact DIs: Trip Multiply, Alarm/Relay Inhibit, Latch Reset, Special Alarm Inhibit, Run Mode, and IP/Account reset. There are two sets of these six inputs on the dual terminal base.

### Channel Types, Sensors, and Measurements



The 3701/44 Aero Monitor supports a set of standard channel types and the common sensors used with those channel types as well as custom configurable sensors. Support for sensor types is dependent on input module type as listed in tables located below in this datasheet section. Each channel type has default measurements that can be enabled or disabled and each channel type can have user customizable nX and bandpass measurements added to the channel and then customized to the application.



The 3701/44 can have up to 12 vibration input channels (Six per input module) and 2 Keyphasor/Speed inputs (One per input module). The monitor supports the channel types listed here:

- Acceleration
- Dynamic Pressure
- Radial Vibration
- Thrust Position
- Velocty
- Keyphasor/Speed

The aeroderivative core section of an aero gas turbine is typically monitored by hightemperature charge-coupled accelerometers that connect to a package mounted interface module consisting of a charge amplifier, signal conditioning, and both acceleration and velocity analog outputs. The acceleration and velocity inputs are treated as their respective channel types in the aero monitor.

## Table 1: Channel Type Support by InputModule

Input Module	Channel Types
PAA	Acceleration
Channels	Dynamic Pressure
1-6	Radial Vibration
	Thrust Position
	Velocity
PAA Channel 7	Keyphasor/Speed (Proximitors, single and multi-event, or Isolated Mag pickup, single and multi- event)
	Acceleration
PAV	Dynamic Pressure
Channels 1-6	Radial Vibration
	Thrust Position
	Velocity
PAV	Keyphasor/Speed (Proximitors,

Input Module	Channel Types
Channel 7	single and multi-event or Mag pickup, single and multi-event)
	Acceleration
PoV	Dynamic Pressure
Channels 1-6	Radial Vibration
	Thrust Position
	Velocity
PoV Channel 7	Keyphasor/Speed (Proximitors, single and multi-event or Mag pickup, single and multi-event).

PAA and PAV channels 1–6 can also be configured to support an additional Keyphasor input provided it is a single event per revolution, less than 5000 rpm, and uses a Proximitor sensor. This cannot be done with the PoV module.



### Input Module Compatibility

## Table 2: Input Module Compatibility withAcceleration Inputs

Input Module	Accelerometer or Accelerometer Interface Module
ΡΑΑ	155023-01 High Freq 200g Accel I/F Module
	23733-03 Accel I/F Module
	24145-02 High-Freq Accel I/F Module
	330400 100 mV/g Accelerometer
	330425 25 mV/g Accelerometer
	330450 High Temp Accelerometer
	350501 Acceleration Charge Amplifier
	350900 High Temp Velocity & Acceleration
	49578-01 Accel I/F Module
	86497 RR Accel I/F Module
	86517 Aero Accel I/F Module (Differential Input)
	Custom
	155023-01 High Freq 200g Accel I/F Module
	23733-03 Accel I/F Module
	24145-02 High-Freq Accel I/F Module
	330400 100 mV/g Accelerometer
PAV	330425 25 mV/g Accelerometer
	330450 High Temp Accelerometer
	350501 Acceleration Charge Amplifier
	49578-01 Accel I/F Module
	Custom
PoV	GSI 122, 124 and 127 Galvanic Interface Unit

Input Module	Accelerometer or Accelerometer Interface Module	
	TP100 Commtest Accelerometer	
	TP500 Commtest Accelerometer	
	200350 Accelerometer	
	200355 Accelerometer	
	786-500 Wilcoxon Accelerometer	
	626B02PCB Accelerometer	
	HS-170 Hansford Accelerometer	
	HS-100F series Hansford Accelerometer	
	CMSS-2100 SKF Accelerometer	
	351M35 PCB Accelerometer	

## Table 3: Input Module Compatibility withVelocity Inputs

Input Module	Velomitors and interface modules
	350900 HTVAS (Velocity)
ΡΑΑ	86497 RR I/F Module (Velocity)
	86517 Aero I/F Module (Velocity – differential input)
	Custom
	330500 Velomitor
	330525 Velomitor XA
	190501 Velomitor CT
	330750 High Temp Velomitor
ΡΑν	330752 High Temp Velomitor
	330505 Low Freq Velocity Sensor
	330530 Radiation Resistant Velomitor
	Custom
PoV	HS-160 Velocity Sensor



## Table 4: Input Module Compatibility withProximity Sensors

Input Module	Proximitor Sensor
PAA or PAV	3300XL 8 & 11 mm
PoV (Keyphasor)	3300XL NSV
	3300 RAM Proximitor
	3300 5 & 8 mm
	3300 16 mm HTPS
	7200 5, 8, 11, 14 mm
	3000 (-24 Volt)
	Custom

## Table 5: Input Module Compatibility withDynamic Pressure Inputs

Input Module	Dynamic Pressure Sensor
ΡΑΑ	3-Wire (Com/Sig/-24VDC) 350500 DPCA or Modified 86517 I/F
PAV	3-Wire (Com/Sig/-24VDC) 350500 DPCA or Modified 86517 I/F
	2-wire PCB 121A21
PoV	2-wire PCB 121A44
	2-wire PCB 121A22

#### **Measurements**

Each channel type has a set of default measurements typical of the channel type. In addition, user customizable nX vectors and bandpass measurements may be added to each channel.

The number of measurements that can be added and enabled depends on the signal processing capability of the processor module. There is no limitation, other than processor performance, to the number of measurements that can be added to a single channel or across all channels. A performance calculator in the BNMC software provides feedback during the configuration process on performance margin as measurements are added or removed and their attributes modified.

Measurement	(2) Configurable Attributes
Radial Vibration	
	Full scale range
	Units (mils or µm peak-peak or rms)
	High pass corner frequency
Direct	Low pass corner frequency
	High pass filter order (1,2,4,6, or 8 <sup>th</sup> )
	Low pass filter order ( 2, 4, 6, or 8 <sup>th</sup> )
	Clamp value (amplitude)
	Full scale range
Rough Load Zone	Units (mils or µm peak-peak or rms) Low pass filter order ( 2, 4, 6, or 8th) Clamp value (amplitude)
	Running Speed
	Full scale range
	Keyphasor association
	Integer or non- integer
IX	order in increments o 0.1x from 0.1x to 100x (phase not valid for non-integer orders).
	Units (mils or µm peak-peak or drms)



Measurement	(2) Configurable Attributes	Measurement	(2) Configurable Attributes
	Clamp value (amplitude and		Keyphasor association
	Full scale range Keyphasor		Integer or non- integer order in increments of 0.1x from 0.1x to 100x
	association Integer or non-		(phase not valid for non-integer orders).
	integer order in increments of 0.1x from 0.1x to 100x		Units (English or metric, peak or drms)
2X	(phase not valid for non-integer orders).		Clamp value (amplitude and phase)
	Units (mils or µm peak-peak or drms)		Integrated
	Clamp value (amplitude and phase)		Full scale range
			Keyphasor association
Gap	Low Pass Corner Frequency Clamp Value (Volts)		Integer or non- integer order in increments of 0.1x
Accelerometer, Veloci	ty	2X	(phase not valid for
	Full scale range		Non-Integer orders).
	Units (English or metric, peak or rms)		metric, peak or drms)
	High pass corner frequency		(amplitude and phase)
	Low pass corner frequency		Integrated
Direct	High pass filter order (1,2,4,6, or 8 <sup>th</sup> )	Bias	Low Pass Corner Frequency
	Low pass filter order (1,		Clamp Value (Volts)
	2, 4, 6, or 8th)	Thrust	1
	Clamp value (amplitude)		Full scale range
	Integrated	Position	Units (mils or µm peak-peak or rms)
١X	Full scale range		Low pass corner



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Measurement	(2) Configurable Attributes	Measurement	(2) Configurable Attributes
	frequency		Frequency
	Clamp value (amplitude)		Clamp Value (Volts)
	Low Pass Corper	<b>Proximitor Speed</b>	
Gap	Frequency	Craced	Top Scale
	Clamp Value (Volts)	Speed	Clamp Value
Dynamic Pressure		Gap	Low Pass Filter Frequency
	Full scale range		Clamp Value (Volts)
	Units (psi or mbar peak-peak, dpp or rms)	Magnetic Pickup Spee	d
	High pass corner	Speed	Top Scale
	frequency		Clamp Value
Pressure	Low pass corner frequency		
	High pass filter order (1,2,4,6, or 8th )		
	Low pass filter order (1, 2, 4, 6, or 8 <sup>th</sup> )		
	Clamp value (amplitude)		
	Full scale range		
Bandpass	Units (psi or mbar peak-peak or rms)		
	High pass corner frequency		
	Low pass corner frequency		
	High pass filter order (1,2,4,6, or 8 <sup>th</sup> )		
	Low pass filter order (1, 2, 4, 6, or 8 <sup>th</sup> )		
	Clamp value (amplitude)		
Bias	Low Pass Corner		



## Table 7: Additional Measurements byChannel Type

#### Measurement

#### Radial Velocity, Thrust, Dynamic Pressure, Accel, Velocity

Bandpass	Full scale range Units (English or metric, peak to peak or rms) High pass corner frequency Low pass corner frequency High pass filter order (1,2,4,6, or 8th ) Low pass filter order (1, 2, 4, 6, or 8th) Clamp value (amplitude)
nX	Full scale range Keyphasor association Integer or non-integer order in increments of 0.1x from 0.1x to 100x (phase not valid for non-integer orders). Units (English or metric, peak to peak or rms) Clamp value (amplitude and phase)
Amplitude Extraction	Full scale range Units (English or metric, peak to peak or rms) Clamp value (amplitude) Associated Spectrum Center Frequency Bandwidth
Spectral Band	Full scale range Units (English or metric, peak to peak or rms) Clamp value (amplitude) Associated Spectrum Start Frequency Stop Frequency

 Technically feasible configurations depend on the interaction between many factors. Certain selections may not be feasible. Use the BNMC software to create an off-line configuration to determine technical feasibility.

2. The default measurement attributes can also be customized.

## Waveforms and Spectral Data

Acquisition of multiple synchronous and asynchronous waveforms can be configured for each 3701 channel in the BNMC software. These waveforms are used as the data source for extraction of measurements that require spectral data such as nX vectors and peak extractions.

Waveform configuration for spectral data consists of  $\rm f_{max}$  and the number of lines in the spectral data.

Asynchronous spectral waveforms:

F<sub>max</sub> can be set between 10 Hz and 40 kHz in 12 discrete steps. F<sub>min</sub> is always at 0 Hz.

The number of spectral lines can be set from 12.5 to 3200 in 12 discrete steps.

Synchronous spectral waveforms:

Number of samples per revolution can be set from 8 to 4096.

Number of revolutions per waveform can be set from 1 to 1024.

#### **Amplitude Extractions**

An Amplitude extraction is the amplitude at a user configured center frequency and with a user configured bandwidth. The band around the center frequency is limited in size and can range from a single spectral line (bucket) closest to the configured center frequency, to the center spectral line plus 5 lines on each side (11 total buckets).

The source data for amplitude extractions are asynchronous spectrums.

Multiple amplitude extractions can be configured on a single channel and across multiple channels.

#### **Spectral Bands**



Spectral bands are user configured with a start and a stop frequency and return the average energy in the band.

The source data for spectral bands are synchronous and asynchronous spectrums using either enveloped spectral or ordinary spectral data.

Multiple spectral bands can be configured on a single channel.

Applications for spectral bands and other signal processing features are described in the Applications section of this datasheet.

## **Alarming and Setpoints**

Alert and Danger over and under alarm setpoints can be created for each measurement individually as well as configurable alarm attributes such as enable/disable, alarm time delay (ATD), and latching/non-latching.

In addition, the alarming attributes (enable/disable, ATD, and latching/nonlatching) can be set independently on the Alert and Danger alarms on the same measurement.

Relay logic is created in the graphical relay logic editor in BNMC software by mapping the enabled alarms to OR and AND gates to drive a relay.

Individual relays can be configured as latching/non-latching or enabled/disabled independently (or in addition to) the settings on the measurement alarms.

## **Network Operation**

The processor module supports two Ethernet RJ45 physical connections located on the terminal base. The two connectors are termed Net A and Net B and each has its own configurable IP address. All configuration and interface to Bently Nevada software and communication using an industrial protocol is using one or both of these connections.

## **Display and HMI Options**

Bently Nevada, LLC offers System 1 Basic as a simple, low cost, easily installed, and light footprint HMI. System 1 Basic is part of the System1 Evolution platform and offers a subset of System\_1\_Evolution functionality to provide a basic operator display.

The Modbus TCP or EGD industrial protocols can be used to serve data to an HMI where users can build display environments using standard 3rd party HMI software.



## Bently Nevada Configuration Software (BNMC)

BNMC software is necessary to configure and verify the 3701/44 Machinery Dynamics Monitor.

BNMC is simple configuration software with a nominal price that is used for monitor configuration. It also has snapshot viewing of time base waveforms (including Keyphasor/Speed) and spectrums to support commissioning and setup of the 3701 and sensor instrumentation system. Bently Nevada Monitor Configuration software will run on most Windows desktop or notebook computers and is designed and fully tested for operation on Microsoft Windows 7 and 8.1 (32 bit and 64 bit) and Microsoft Windows 2008 and 2012 Server (64 bit).

Language support at the current time is English version operating systems with keyboard preference set to English.

BNMC is ordered separately from the monitor hardware. See the spares section in the Specifications portion of this datasheet for the part number.

### System\_1\_Evolution Connectivity

3701 monitors connect to System\_1\_Evolution and support current value and time-based data collection of all static values, waveforms, and spectral data. This includes System 1 software's full suite of plots and tools for conditioned monitoring and asset management.

When an event is triggered on the 3701/4x monitor, the following high resolution alarm data is forwarded to System 1(\*).

#### **Trended Measurements:**

	Duration	Intervals
Pre-event Data	10 minutes	1 second
	20 seconds	100 milliseconds

	Duration	Intervals
Post-event	10 seconds	100 milliseconds
Data	1 minute	1 second

#### Spectrums/Waveforms:

	Duration	Intervals
Pre-event Data	2.5 minutes	10 seconds
Post-event Data	1 minute	10 seconds



In case of network disruption between the 3701 and System 1, the 3701 can store up to 512MB of Alarm data and 512MB of transient data.

\* Requires System\_1\_Evolution 17.2 or newer and Firmware release 4.1 or newer for 3701/4x.

## **Applications**

This section describes selected applications where the 3701 functions and features offers particular benefits.

#### **Dual Redundant Protection**

A typical dual redundant protection only application has these basic elements:





- Each processor module processes all sensor and Keyphasor input signals and has communication (Ethernet) connections only to the controls and automation system.
- Each processor is configured the same and executes identical logic.
- Processor module 1 drives relays 1, 3, 5, and 7. Processor module 2 drives relays 2, 4, 6, and 8. The same alarm logic is used for each relay pair (1, 2), (3,4) etc.
- An external shutdown system connects to relay pairs and votes loo2 or 2002 depending on application requirements. (The loo2 configuration is for SIL 2 applications.)
- The dedicated protection fault relay is driven by a protection fault in either of the processor modules and is driven if one processor module is removed.
- If redundant sensors are required, they can be voted 2002 or 1002 in the 3701 processor modules. SIL 2 applications require voting the 3701 relays 1002 in an external ESD but the sensor alarm voting in the 3701 processors provides the 2002 vote.
- System configuration can be varied in a number of ways to meet different reliability requirements. Redundant sensors can be used partially or entirely. Non-redundant sensor points, such as XY radial shaft vibration probes, on the same bearing can also be split between input modules.
- Redundant industrial protocols can operate independently from each processor module to automation and control systems.

#### Dual Redundant Protection with a System 1 Connection

This optional configuration operates the same as described above but Processor Module 1 connects to System 1 using one of its Ethernet ports. Cyber security is the key design element that must be addressed in this configuration.



## Radial Shaft Vibration, Axial Position, and Casing Vibration

3701 supports the standard industry measurements for these applications but, in addition, users can create custom measurements on these channels using spectral bands, bandpass timebase measurements, amplitude extractions, nX measurements, integrated and nonintegrated, and rms or peak measurements.

Detection of certain mechanical, aerodynamic, and hydraulic, faults can be enhanced by improved measuring capability. For example, on an axial compressor there may be



increased sub-synchronous axial vibration at the onset of a surge condition – a bandpass timebase measurement or synchronous spectral band measurement on an axial position probe can enhance detection of this specific fault mode.



#### **Roller Element Bearings**

Use spectral bands to focus on bearing fault frequencies. (nX measurements can also be used but the spectral band allows customizing the bandwidth to the bearing fault frequency response whereas the nX measurement is narrow band.)

Outer Race Ball Pass (ORBP)	A spectral band using synchronous enveloped or non- enveloped data can be set around the expected ORBP
Inner Race Ball Pass (IRBP)	A spectral band using synchronous enveloped or non- enveloped data can be set around the expected IRBP
Cage	A spectral band using synchronous enveloped or non- enveloped data can be set around the expected cage frequency
Ball Spin 1X	A spectral band using synchronous enveloped or non- enveloped data can be set around the expected ball spin 1X frequency
Ball Spin 2X	A spectral band using synchronous enveloped or non- enveloped data can be set around the expected ball spin 2X frequency
Overall and non-REB fault frequencies	Set one or more bandpass measurements to look at overall vibration at frequencies where rotor, casing, or structural vibrations are expected.
	used for rotor related vibration.
HF band	Set a spectral band using enveloped synchronous or asynchronous data sources on a broader high frequency band to detect low level impact events.
	(A simple banapass with an

100M8649 Rev. R

appropriately set high pass filter can be configured in addition.)

#### **Gear Boxes**

There are many types of gear boxes with correspondingly different vibration monitoring needs. This short section is intended only to highlight some particular features of the 3701 system.

Feature	Description
Gear Mesh (GM) 1X, 2X, or 3X	Set a synchronous spectral band, or an nX measurement (or both) on the 1X, 2X, and 3X GM. For each gear set.
Gear Mesh Side Bands	If you know the fundamental frequency of an expected side band based on the gear kinemantics, then you can set a synchronous spectral band on a specific sideband.
Enhanced measurements from Radial Vibration Proximitors	For API 613 gearboxes where XY radial vibration probes are typically specified the Technician can set the GM related spectral bands described above as well as nX's based on hi and low speed shaft Keyphasors.
Enhanced measurements from Thrust Position Proximitors	For API 613 gearboxes where axial position probes are typically specified. Axial vibration can be measured by setting bandpass filtered or nX measurements in addition to the conventional thrust position measurement.

## Gas Turbine Combustion Dynamic Pressure



Spectral bands and/or amplitude extractions as well as bandpass filtered timebase measurements can be configured to selectively monitor the different tones produced by

pressure pulsations in combustion turbines.



## Specifications

#### 3701/44 Monitor Power Requirements

Input Voltage		
Minimum	18 Vdc	
Maximum	36 Vdc	
Current		
Simplex	2.3 amps max current	
Duplex	3.0 amps max current	
Inrush Current	3.0 amps max inrush less than 5 mS (Per processor card)	

Supply must be 2006/95/EC Low Voltage Directive compliant for CE installations.

Supply must be Class I, Div 2 or Class I, Zone 2, (CL2 SELV), compliant for hazardous area Installations.

### 3701/44 Processor Module Specifications

Inputs		
Maximum	12 dynamic signals and 2 Keyphasor/speed signals	
Signal/Noise Ratio	110 db @ 102.4 ksps	
A/D Conversion	Sigma- Delta 24 bit	
Bandwidth	0.5 to 40 Khz	
Outputs		
Two Independent Ethernet ports		
Net A	10/100 BaseT	
Net B	10/100 BaseT	

Buffered Signal Outputs	15 pin DSUB connector, available accessory cable for BNC and SMC options. 550 ohm output impedance
LEDs	
Module OK LED	Indicates when the module is functioning properly
Protection FaultLED	Indicates that the monitor has experienced a fault that is affecting protection
User Inhibit LED	Indicates that there has been a user initiated inhibit of alarming functionality
Attention LED	Indicates a condition on the monitor has occurred that may require action
Danger LED	Indicates a Danger condition
Alert LED	Indicates an Alert condition
KPH 1 OK LED	Indicates that Keyphasor signal 1 is triggering
KPH2 OK LED	Indicates that Keyphasor signal 2 is triggering
Net A	Indicates that Network A has a valid link
TX/RX A	Indicates that network traffic is flowing on Network A
Net B	Indicates that Network B has a valid link
TX/RX B	Indicates that network traffic is flowing on Network B
PWR 1 OK	Indicates that the first power input is functioning correctly
PWR 2 OK	Indicates that the second power input is functioning correctly



### Accuracy

Direct pk or rms	Within ± 0.5% of full-scale typical
	1.1% worst case
Bias	+0.4 V / -0.8 V typical
	+0.8V / -1.34 V worst case.
Tracking Filters	nX tracking filters are have a bandwidth of 0.075X, where X is the speed of the associated speed channel.

## Alarming

Setpoints	Over/under user configurable
Time Delay	100 mS – 60 minutes
Latching	User configurable alarming or relay latching

## 3701/44 Environmental Specifications

#### Indoor Use Only

Operating Temperature Range

Ø

-30°C to +65°C† (-22°F to 149°F)

†If the 3701 is operated 100% at +65°C, its life will be reduced to approximately 11 years. Any portion of the time it is operated below +65°C or any convective airflow will increase its lifespan

Storage Temperature Range	-40°C to +85°C (-40°F to 185°F)
Relative Humidity	0% to 95% rH non- condensing Operating and Storage
Vibration	5 g @ 57-500 Hz.

	IEC 60068-2-6
Shock	15 g, 11 ms
Altitude	< 2000 m (6,562 ft)
Pollution Degree	Pollution Degree 2
Installation Category	Category II

## Physical

Simplex Base	
Dimensions	26.7 x 20 x 18.2 cm (10.5 x 7.87 x 7.15 in)
Weight	4.5 kg (9.9 lbs)
Mounting	Bulkhead 4 mounting bolts or screws at corners.



- 2015 Steel Vessels Rules
- 2015 Offshore units and Structures

### Compliance and Certifications

#### FCC

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- This device may not cause harmful interference.
- This device must accept any interference received, including interference that may cause undesired operation.

#### **EMC**

EN 61000-6-2

EN 61000-6-4

EMC Directive 2014/30/EU

#### **Electrical Safety**

EN 61010-1

LV Directive 2014/35/EU

#### **RoHS**

RoHS Directive 2011/65/EU

#### ATEX

EN 60079-0

EN 60079-15

ATEX Directive 2014/34/EU

#### **Cyber Security**

Achilles Communications Certification Level 1

#### Maritime

ABS 2009 Steel Vessels Rules

1-1-4/7.7,4-8-3/1.11.1,4-9-7/13

Complies with ABS Rules for Condition of Classification, Part 1



## Hazardous Area Approvals

For the detailed listing of country and product specific approvals, refer to the *Approvals Quick Reference Guide* (108M1756) available from www.Bently.com.

## CSA/NRTL/C

Class I, Zone 2: AEx nA nC IIC T4 Gc; Class I, Zone 2: AEx ec nC IIC T4 Gc; Class I, Division 2, Groups A, B, C, and D;

T4 @ Ta=  $-30^{\circ}$ C to  $+65^{\circ}$ C When installed per drawing 100M1872

### ATEX/IECEx



ll 3 G Ex nA nC llC T4 Gc

T4 @ Ta= -30°C to +65°C

ATEX Special Conditions of Safe Use

- The equipment shall only be used in an area of not more than pollution degree 2, as defined in IEC 60664-1.
- The equipment shall be installed in an enclosure that provides a degree of protection of not less than IP54 and which meets the enclosure requirements of EN 60079-0 and EN 60079-7/EN 60079-15. The enclosure shall be suitable for an ambient temperature range of -30°C to +65°C and a service temperature of 80°C.
- Transient voltage protection shall be provided by the external circuits to ensure that transient overvoltages to the equpment cannot exceed 140% of 85 V.

- When installed in a metal enclosure, the enclosure shall have an external facitlity for an earth bonding connection which complies with EN 60079-0:2012/A11:2013 clause 15.1.2 and which is electrically in contact with the internal earth connection facility on the equipment.
- The relay output circuits shall not be connected to circuits which exceed 30V, 5A.



## **Ordering Information**

For the detailed listing of country and product specific approvals, refer to the *Approvals Quick Reference Guide* (108M1756) available from Bently.com.

The 3701/44 ADAPT Aeroderivative Monitor can be ordered as an individual component or as part of a kit that may include other components than just the monitor. Ordering part numbers are provided below for both options.

Use the 3701/44 part number below to order the Aero Monitor.

## 3701/44-AA-BB-CC-DD-EE

#### A: Redundancy

	,	
01	Simplex	
02	Duplex	
B: Input Module 1		
01	Prox/Accel/Velom	
03	Prox/Accel/Aero	
04	Positive Input Mod.	
C: Input Module 2		
01	Prox/Accel/Velom	
03	Prox/Accel/Aero	
04	Positive Input Mod.	
D: Output Module		
00	None	
01	8 CH Relay Module	
E: Approvals		
00	None *	
01	CSA	
02	ATEX/IECEX	
	1	

#### XX Country Specific

\* This does include the nonhazardous area general safety certification

#### **Spares**

Part Number	Description
3701/44	3701/44 Aeroderivative Monitor
177896-01	3701/44 Processor Module
177990-01	Prox Accel Aero (PAA) Module
177989-01	Prox Accel Velom(PAV) Module
105M6001-01	Positive Input (POV) Module
177897-01	3701 Output Relay Module
175794	3701 Simplex Terminal Base
178372-01	3701 Duplex Terminal Base
177992-01	3701 Terminal Block – Standard
100M9465-01	BN Monitor Configuration SW DVD

#### Accessories

Part Number	Description
323314-01	Buffered Output cable 15 pin D- Sub to 7 SMA connectors. (SMA connectors work with the ADRE 408)
323314-02	Buffered Output cable 15 pin D- Sub to 7 BNC connectors
324343	Weatherproof Housing Kit
Bently_ Manuals	Customer DVD containing all Bently Manuals, FWD, App Notes, and Install Guides in all available languages



## **Graphs and Figures**



- 1. Processor Module
- 2. Input Module 1
- 3. Input Module 2
- 4. Output Module
- 5. Terminal Base

#### Figure 1: 3701/44 Simplex Terminal Base Top View





- 1. Processor Module(s)
- 2. Input Module 1
- 3. Input Module 2
- 4. Output Module
- 5. Terminal Base

#### Figure 2: 3701/44 Duplex Terminal Base Top View



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