

# FusionPro™ Intelligent Production Drive

## Quick Start Guide

---

# Legal Information

Copyright 2024 Baker Hughes Company. All rights reserved.

The information contained in this document is confidential and proprietary property of Baker Hughes and its affiliates. It is to be used only for the benefit of Baker Hughes and may not be distributed, transmitted, reproduced, altered, or used for any purpose without the express written consent of Baker Hughes.

## Third Party Trademarks

<b>Mark</b>	<b>Company</b>
MOXA®	Registered trademark of Moxa Inc.

Revision History					
Rev.	PR	Amendment Detail	Reviewer	Approver	Effective Date
<b>Current Revision</b>					
A	105606	Initial Release	Plitt, Sheldon; Dowhower, Matt; Burkhart, Damon	Hillshafer, Jeremy W	1 Oct 2024
<b>Three Previous Revisions</b>					

**Table of Contents**

**Legal Information ..... 2**

**Before you begin... 5**

    Why a Quick Start Guide (QSG)? ..... 5

**Safety & Security ..... 6**

**Be aware of... 7**

        Hazards associated with the equipment ..... 7

        General Safety Best Practices..... 8

**General Information..... 9**

**General Information ..... 10**

        Nameplate Information ..... 10

        FusionPro™ – Outside View ..... 11

        FusionPro™ Controls ..... 12

        FusionPro™ – Inside View..... 13

        Field Connections..... 14

**Hardware (How do I...)..... 15**

**How do I... ..... 16**

        Make sure the equipment is grounded..... 16

        Connections at the Customer Interface Panel..... 17

        I/O Module and Customer Interface Connections ..... 18

        Connect a Zenith gauge to the drive..... 20

        Connect External Devices to FusionPro™ Communication Interfaces..... 21

**Software (I want to...) ..... 22**

**I want to..... 23**

        Navigate the display ..... 23

        Set Up a New User Profile ..... 24

        Set Up Wi-Fi..... 25

        Set Up Time and Zone ..... 26

        Perform a Basic Set-Up..... 27

        Set-up I/O module..... 28

        Set-up a Zenith DH Sensor..... 29

        Make Sure the Drive is Ready to Start..... 30

        Set-up a digital input to create a drive alarm..... 31

**Reference Information..... 32**

---

# Before you begin...

## Why a Quick Start Guide (QSG)?

Thank you for purchasing a Baker Hughes FusionPro™ Variable Speed Drive (Drive).

This QSG provides you with the minimum information about your purchase to safely and quickly perform the most common tasks required to begin producing with an ESP System.

What you will not see in this guide are any detailed explanations of how things operate or any instructions on tasks that require an authorized electrical worker to perform them. The QSG is intended for the qualified end user only. If you are looking for that type of information, then you must review the companion documents to this QSG.

Companion documents to this QSG are the following three manuals:


- FusionPro™ Operations Manual
- FusionPro™ System Controller Manual
- FusionPro™ Troubleshooting Manual

The above manuals are available digitally on any hand-held device or computer by scanning the QR code in the Reference Information section of this guide.




# Safety & Security

# Be aware of...

## Hazards associated with the equipment

 **DANGER**

**HAZARD OF ELECTRICAL SHOCK OR BURN**

- Ensure Earth ground is properly bonded prior to any contact with this equipment.
- Only qualified personnel are allowed to open and service this equipment.
- Arc-Flash Hazard: Never apply power or operate the equipment with doors or covers open.
-  - Serious or fatal electrical shock may result from failure to isolate the incoming power from the drive's electrical power source.
-  - Always Lock-Out/Tag-Out (LOTO) all incoming power at the source/utility before opening the enclosure to create a safe work condition (per NFPA 70E Article 120). Be aware there may be multiple power sources present. Verify the absence of voltage by wearing the proper safety equipment equivalent to Hazard Risk Category 2 garments and high-voltage safety gloves.
-  - Allow at least 5 minutes for bus capacitors to discharge or until the voltage is less than 50V prior to opening the enclosure.
- This equipment may contain SCADA or telemetry connections causing automatic starting. To prevent unexpected starts, always Lock-Out/Tag-Out (LOTO) equipment before servicing.
- Connected downhole motor may generate back-fed voltage. Once all drive's incoming power is removed, isolate downhole motor power potential at the vented junction box prior to servicing.

**NOTICE**

This system is equipped with a Wi-Fi access point that provides the ability to monitor data and configure settings via remote devices within the Wi-Fi range.

If the Wi-Fi functionality is enabled, the SSID and Wi-Fi password **MUST** be changed from default settings to ensure system security and prevent unauthorized access.

---

## General Safety Best Practices

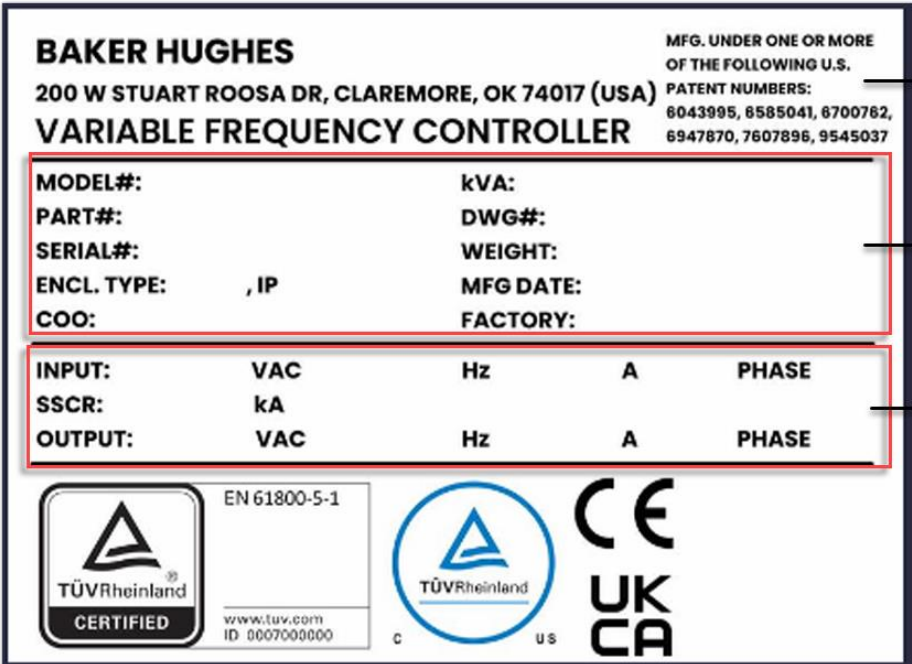
- FusionPro™ uses potentially lethal voltages. Only competent qualified personnel are permitted to install, maintain, or perform repair services.
- Any work requiring access inside the enclosure must be performed with the power off. Users must understand all the hazards, use proper Lock-Out/Tag-Out (LOTO) procedures and Personal Protective Equipment (PPE) to ensure personnel safety. For more details, refer to NFPA 70E Article 120.
- The installation must follow all local and national electrical codes and regulations.
- Any unauthorized modifications not provided, installed, or approved by Baker Hughes may result in the following:
  - injury or death
  - serious property or environmental impact
  - damage or failure of the equipment
  - voiding the unit certification
  - voiding the product warranty
- Baker Hughes is not responsible for any unauthorized use of the equipment; such use may impede physical and software protections provided by the equipment.



# General Information

# General Information

## Nameplate Information



**BAKER HUGHES**  
 200 W STUART ROOSA DR, CLAREMORE, OK 74017 (USA)  
**VARIABLE FREQUENCY CONTROLLER**

MFG. UNDER ONE OR MORE OF THE FOLLOWING U.S. PATENT NUMBERS:  
 6043995, 6585041, 6700762, 6947870, 7607896, 9545037

<b>MODEL#:</b>	<b>kVA:</b>
<b>PART#:</b>	<b>DWG#:</b>
<b>SERIAL#:</b>	<b>WEIGHT:</b>
<b>ENCL. TYPE:</b> , IP	<b>MFG DATE:</b>
<b>COO:</b>	<b>FACTORY:</b>

<b>INPUT:</b>	<b>VAC</b>	<b>Hz</b>	<b>A</b>	<b>PHASE</b>
<b>SSCR:</b>	<b>kA</b>			
<b>OUTPUT:</b>	<b>VAC</b>	<b>Hz</b>	<b>A</b>	<b>PHASE</b>

EN 61800-5-1

TÜVRheinland CERTIFIED

www.tuv.com ID 0007000000

TÜVRheinland

CE

UK CA

1

2

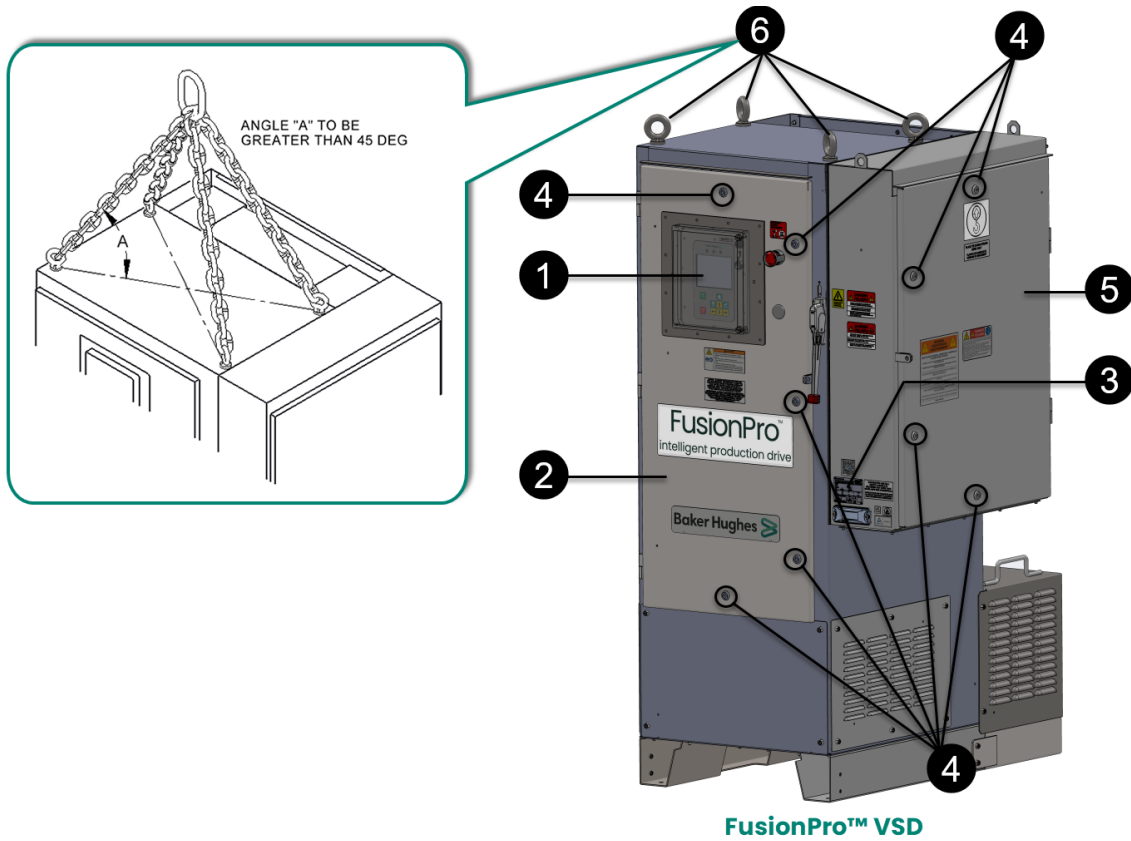
3

1 VSD Nameplate

2 VSD Physical Properties

3 VSD Electrical Ratings

# FusionPro™ – Outside View



**1** Navigation Display & Control Interface

**2** VSD Front Door

**3** Nameplate

**4** Rotolocks

**5** Junction Box Door

**6** Hoisting / Strapping Points

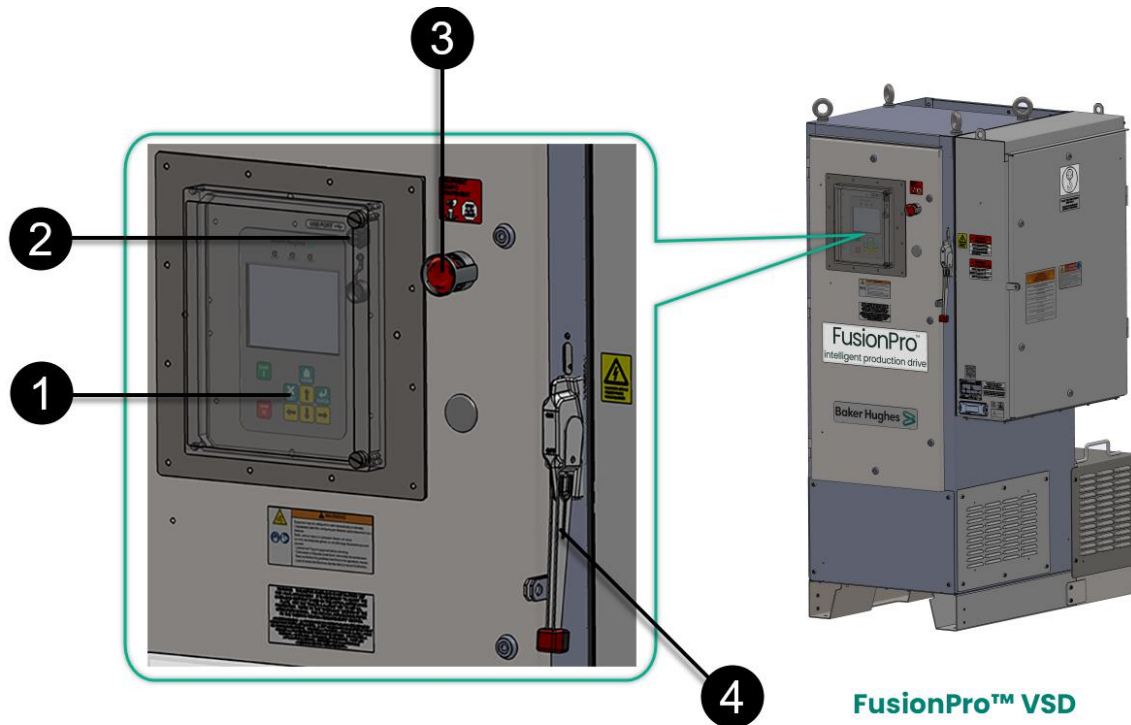
**Note:** All hoisting and strapping of the VSD for shipment to be done using the Hoisting / Strapping points only. Refer to the FusionPro™ Operations Manual for more information.

**Note:** In order for the main cabinet and the junction box to be sealed, all the Rotolocks must be turned in the clockwise direction.

## Operational Clearance

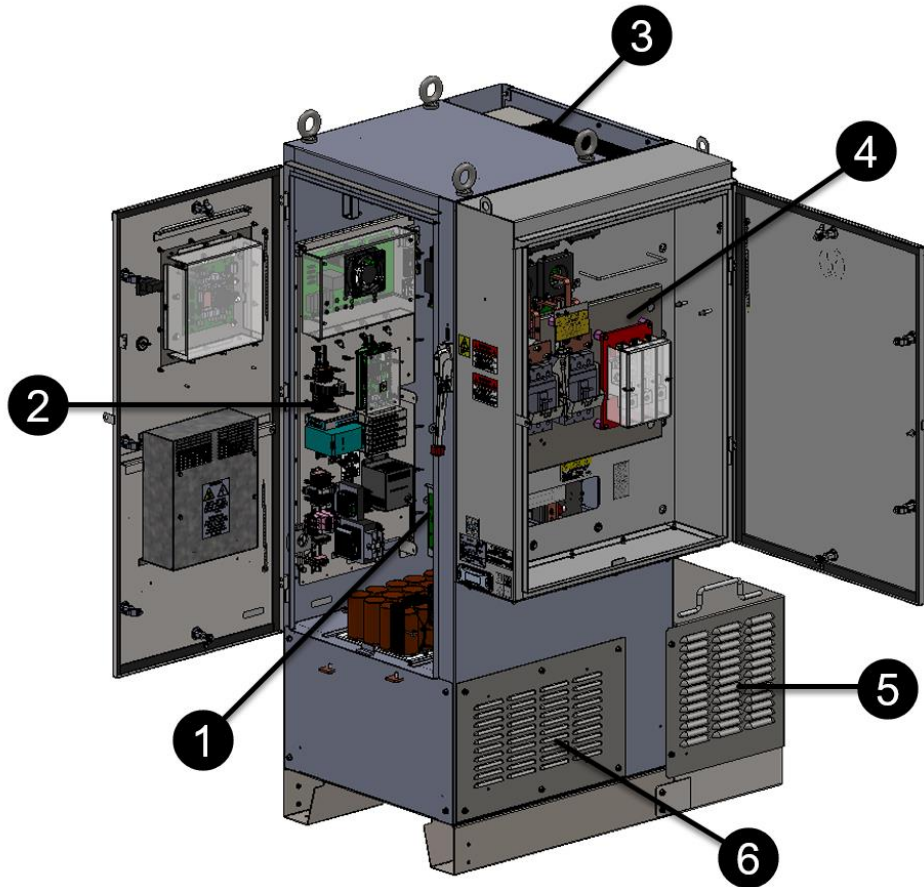
FusionPro™ is equipped with weatherproof enclosure (NEMA 4, IP56), and is suitable for outdoor installations in non-classified/nonhazardous locations. Allow a minimum of 48 in. (1.22 m) clearance in the front and the rear of the enclosure for servicing and air flow requirements. Never install the drive close to heat generating sources such as transformers or other drives. It is necessary to have an unrestricted supply of cooling air (55°C/131°F maximum) to the cooling fan(s) mounted to the back of the enclosure. Ensure adequate distance is allotted on the sides of the enclosure for proper ventilation and opening of the junction box door. See FusionPro™ Operations Manual for more details.

# FusionPro™ Controls



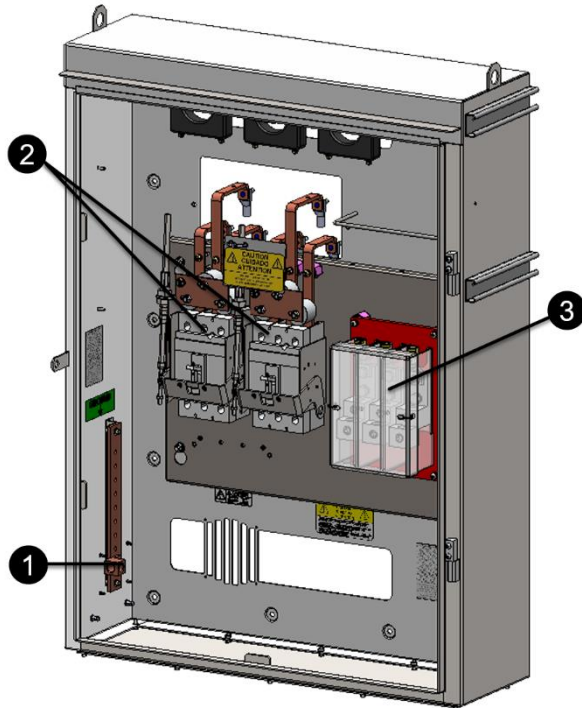
- 1 Navigation Display & Control Interface
- 2 USB Port
- 3 Equipment Stop
- 4 Power ON/OFF

## FusionPro™ – Inside View

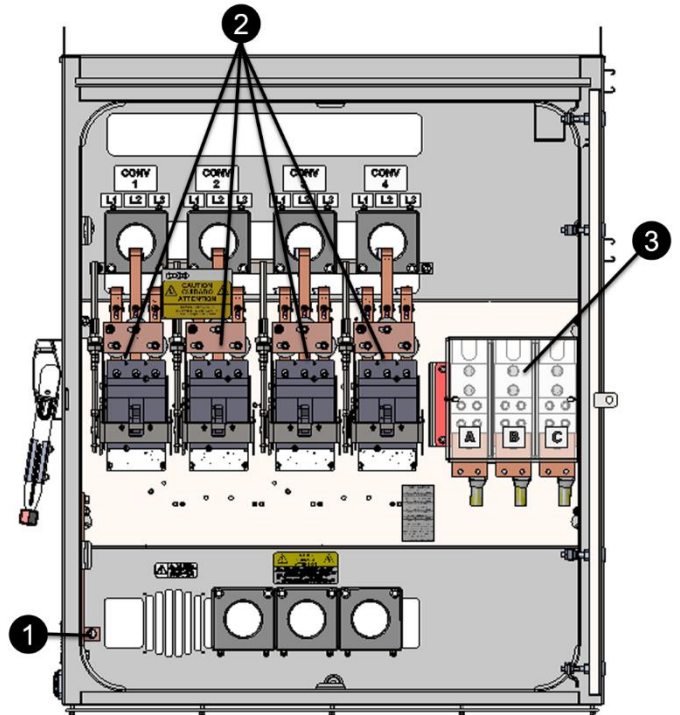


- 1 Main Cabinet
- 2 Customer Interface Panel (CIP)
- 3 Heat Exchanger Plenum
- 4 Power Junction Box
- 5 SWF Louver
- 6 DCL Louver

# Field Connections



VSD Model 2000 - Input/Output  
Connection Points



VSD Model 4000 - Input/Output  
Connection Points

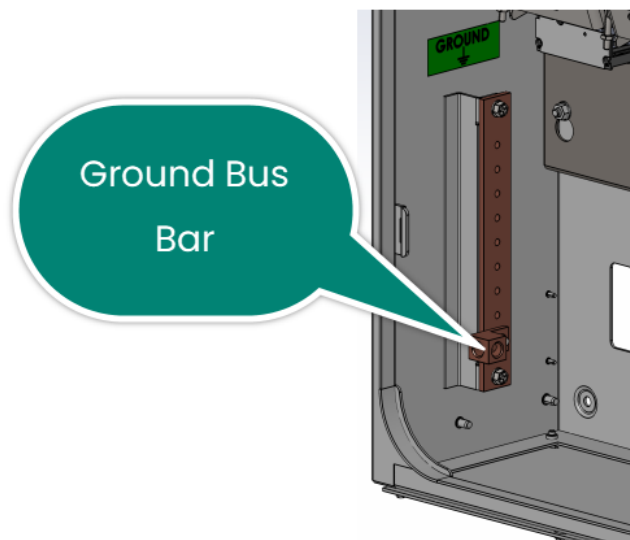
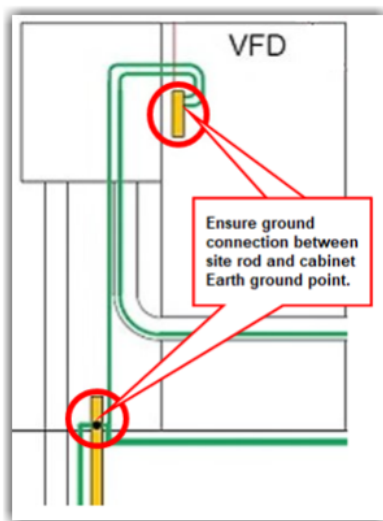
- 1** GND BAR
- 2** Input
- 3** Output



# Hardware (How do I...)

# How do I...

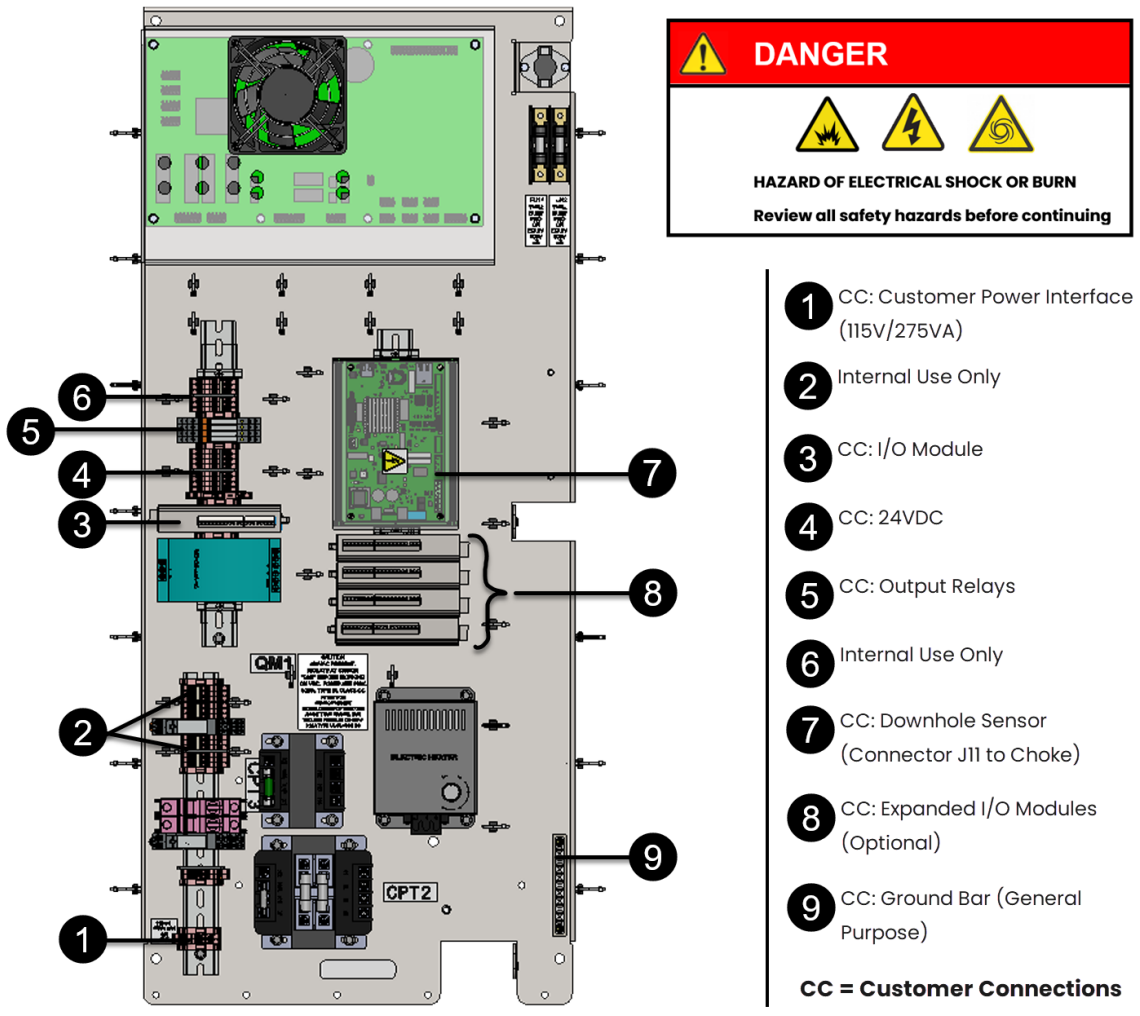
## Make sure the equipment is grounded



1. Open junction box on the left side of the cabinet.
2. Visually verify that the Earth ground wire is bolted to the ground bus bar.



# Connections at the Customer Interface Panel



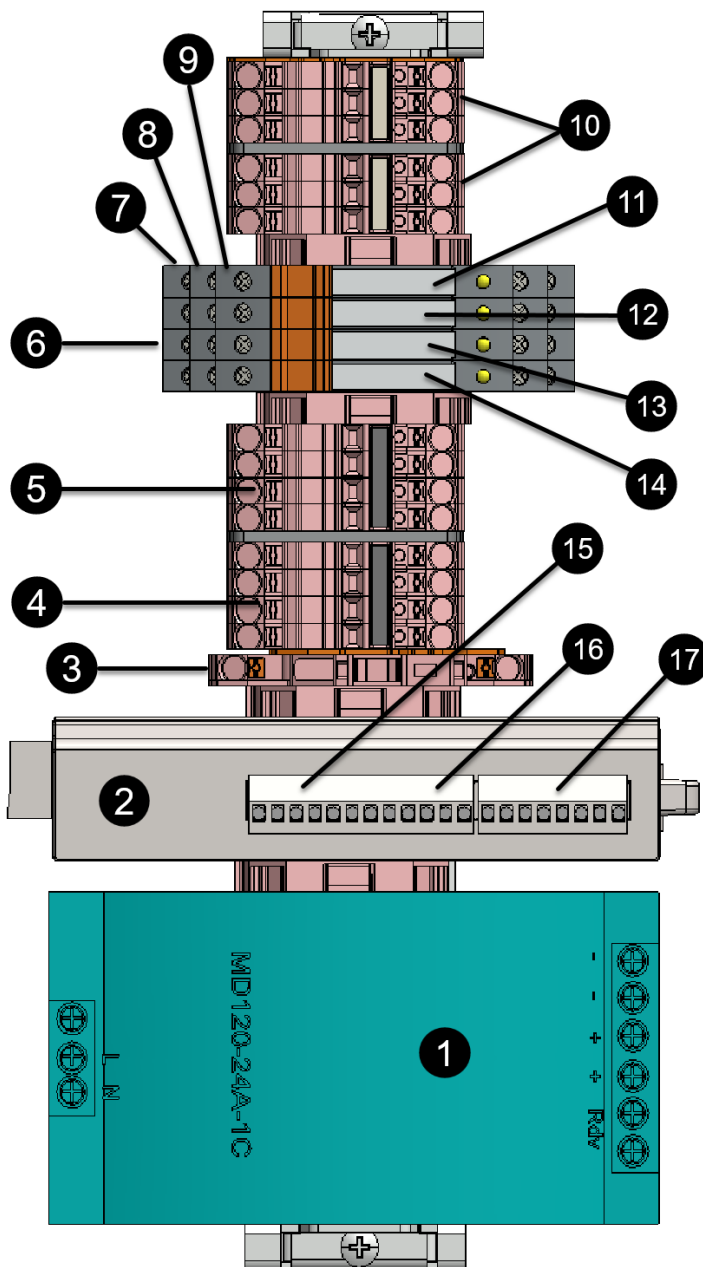
1. Do not make connections at interface points that are not specified for customer use.

2. Use only wires and cables that are rated for the voltage class and current requirements of the related circuit. Insulation must be at a minimum 90°C and flame rated.

3. Route wires and cables carefully to prevent mis-matched insulation ratings. It may be necessary to double insulate low-voltage wire and cable with 600V class tubing sleeves.

4. Wiring that exits the enclosure shall use glands or fixtures that maintain NEMA-4 integrity.

# I/O Module and Customer Interface Connections



- 1 PS2 (24V/5A)
- 2 MX1 (E1242)
- 3 FU20 (4A/250V, C48109 [Mersen #GDG-4])
- 4 CC: TB23 A-D (24V-)
- 5 CC: TB24 A-D (24V+)
- 6 CC: Digital Output (DRY 250V/6A)
- 7 CC: RLY Connection - 11 (COM)
- 8 CC: RLY Connection - 14 (NO)
- 9 CC: RLY Connection - 12 (NC)
- 10 For Internal Use Only
- 11 RLY24
- 12 RLY23
- 13 RLY22
- 14 RLY21
- 15 Digital Output (To RLY21-RLY24) (PINS 16-20)
- 16 CC: Digital Input (PINS 9-13)
- 17 CC: Analog Input (PINS 1-8)

**CC = Customer Connections**

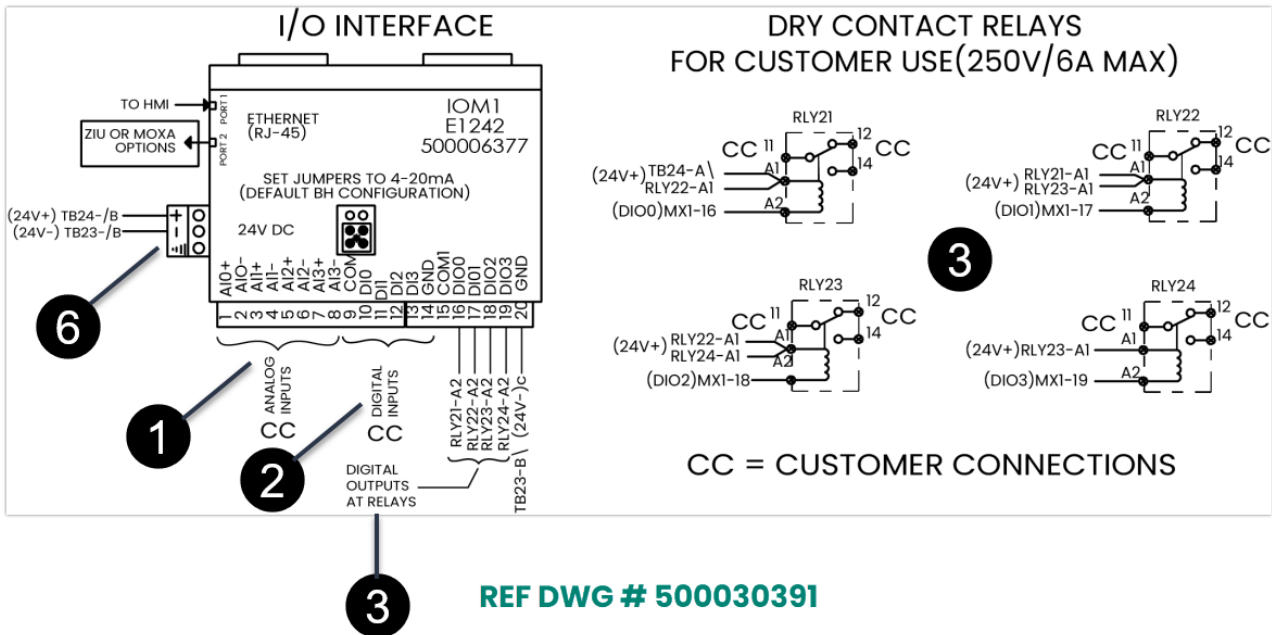
**⚠ DANGER**



HAZARD OF ELECTRICAL SHOCK OR BURN

Review all safety hazards before continuing

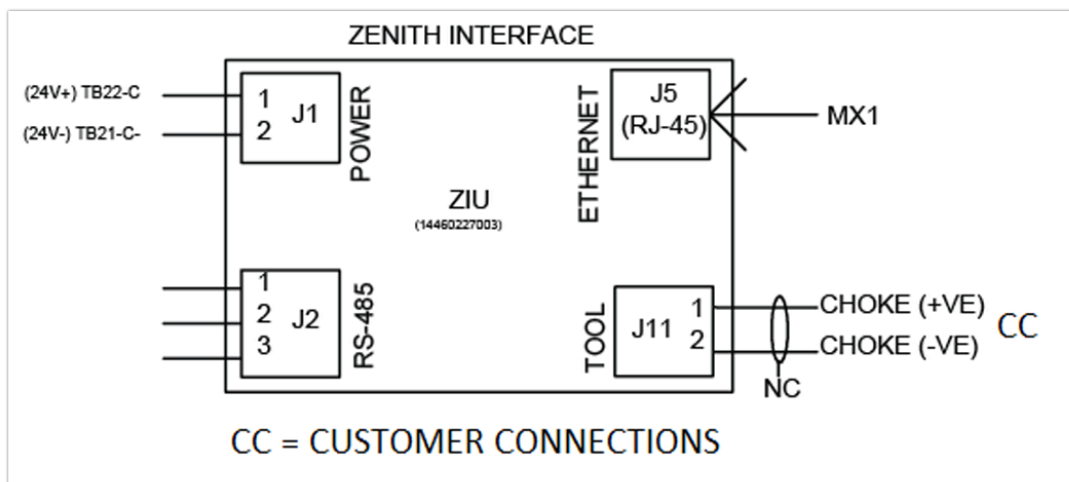
Continue...



- 1** Install devices for analog input directly to Moxa module at paired inputs located at terminals 1 through 8.
- 2** Install devices for digital input directly to Moxa module at inputs located at terminals 10 through 14, using terminal 14 as the common connection for each input.
- 3** Install devices for digital output to relays 21 through 24 at common terminal 11 to NC terminal 12 or NO terminal 14.
- 4** Recommended torque for Moxa terminals is 3.0 lb-in (0.34 N-m).
- 5** Recommended torque for relay terminals is 4.9 lb-in (0.55 N-m).
- 6** 24Vdc power is available at terminal blocks TB23(-) and TB24(+). Do not exceed 2A load.

**Note:** Refer to the FusionPro™ Operations Manual for recommended enclosure penetration, wire size / type details, etc.

# Connect a Zenith gauge to the drive

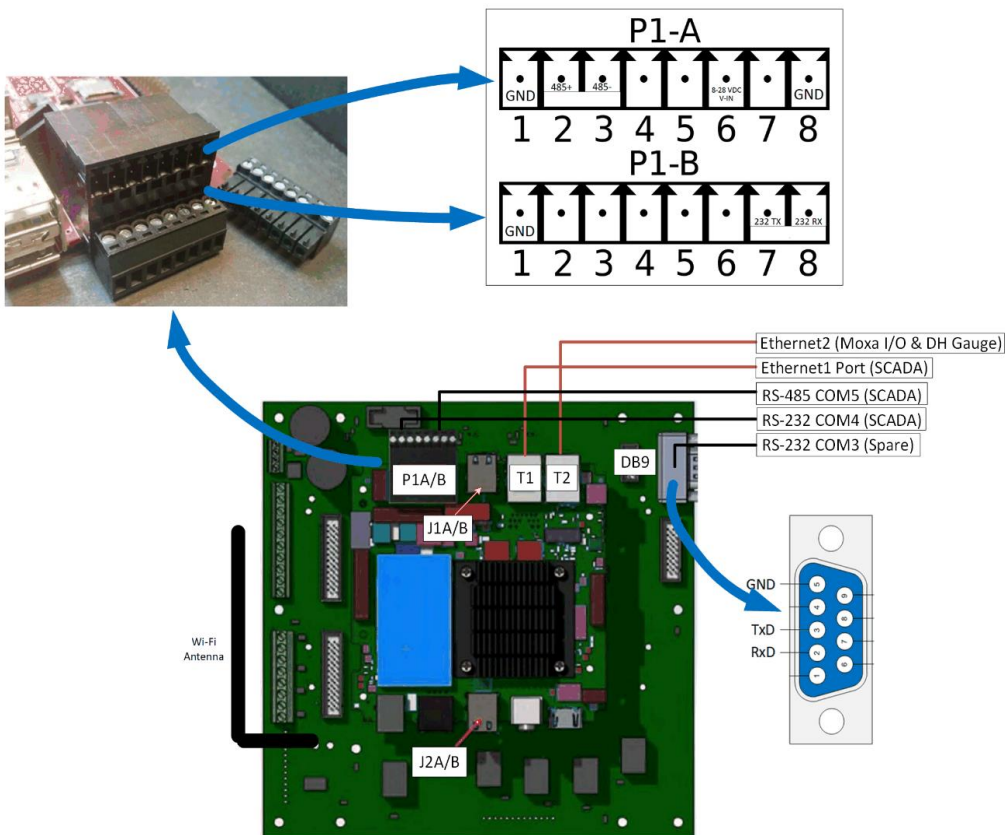


REF DWG # 500030391

- 1 Route appropriate cable from Zenith Choke to ZIU-PCBA, avoid cable routing near motor-power and low-voltage-control wires of the VSD.
- 2 Install the sensor / choke positive connection to J11-1 of the ZIU-PCBA.
- 3 Install the sensor / choke negative connection to J11-2 of the ZIU-PCBA.
- 4 The cable's shield should be bonded to ground near the choke, not inside the drive.

**Note:** Refer to the FusionPro™ Operations Manual for recommended enclosure penetration, wire size / type details, etc.

# Connect External Devices to FusionPro™ Communication Interfaces

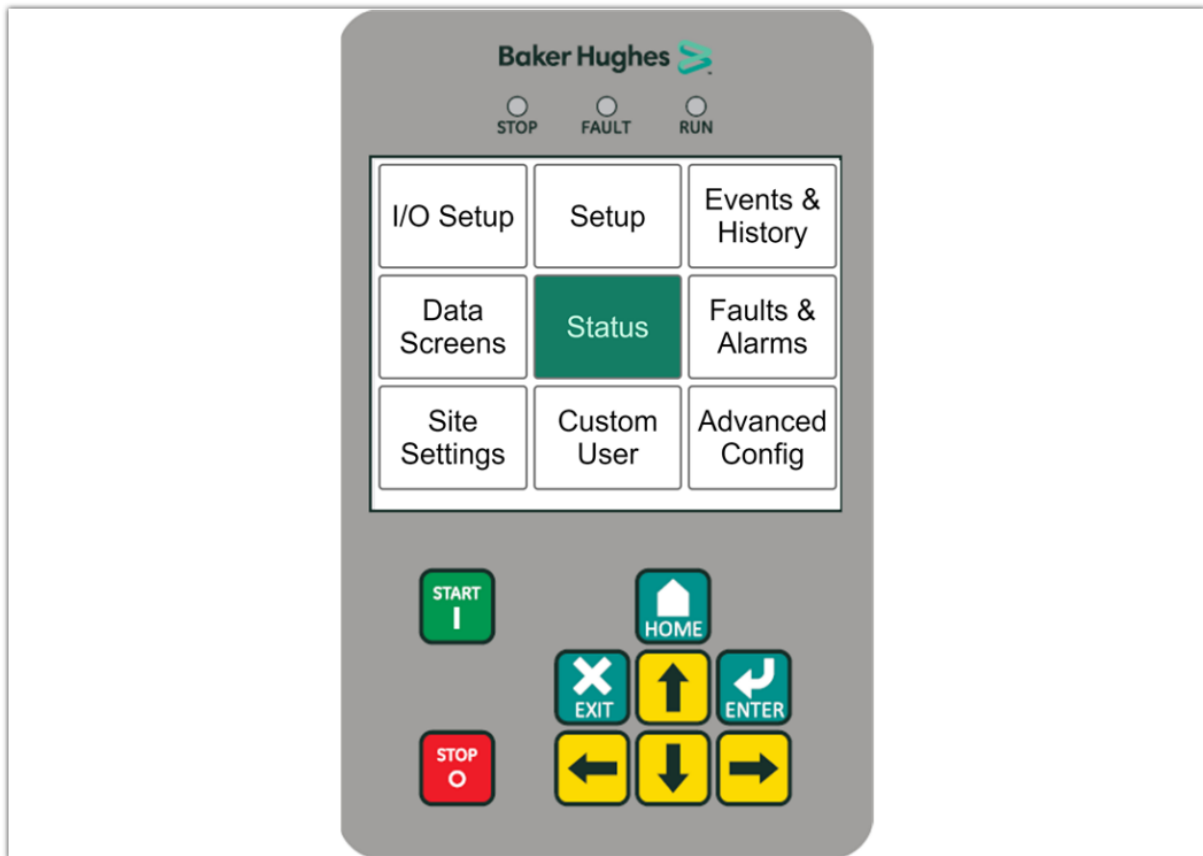



- 1** The RJ-45 jack at **T1** can be used for Ethernet communications with the HMI.
- 2** The screw-terminal connections at **P1A/B** can be used to make:
  - (a). RS485 connections: [RS485- to P1A-3]; [RS485+ to P1A-2]
  - (b). RS232 connections: [Dig\_Gnd to P1B-1]; [RS232\_RXD to P1B-8]; [RS232\_TXD to P1B-7]
  - (c). Recommended torque for P1 terminals is 3.0 lb-in (0.34 N-m).
- 3** **J2A/B** is the USB interface, and one port is cabled to the connector on the outer surface of the HMI. This port is used to download and upload the FusionPro™ information to the HMI.
- 4** Always route communications wires away from other circuits to avoid crosstalk and interference from electromagnetic noise.


# Software (I want to...)


# I want to...

## Navigate the display





 HOME - return to the **Main** menu (Gang-of-Nine) in the menu system

 ENTER - select and option to enter edit mode on an editable parameter

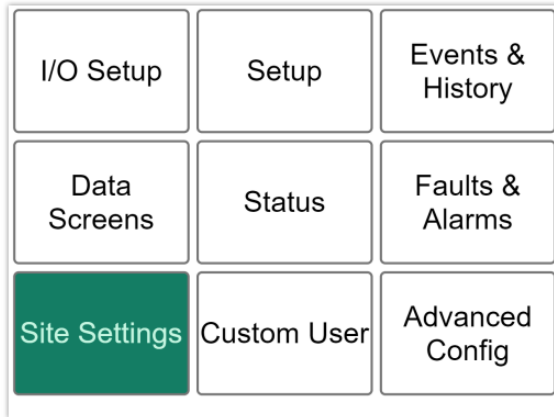
 START - advance the motor to the next Start state

 STOP - stop the motor

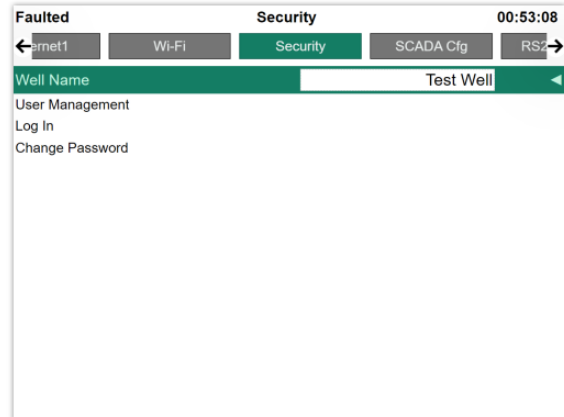
 EXIT - back out of edit mode or screen entry

 Up, Down, Left, and Right - arrow keys for cursor movement

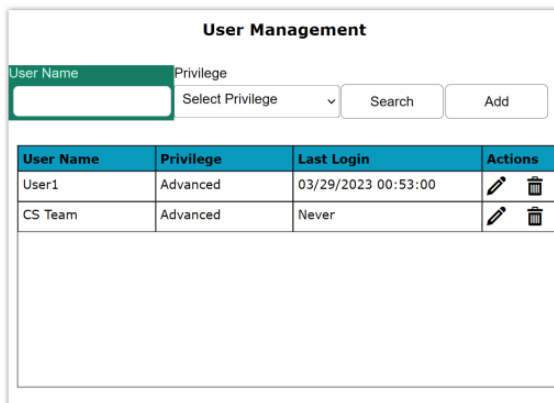
# Set Up a New User Profile



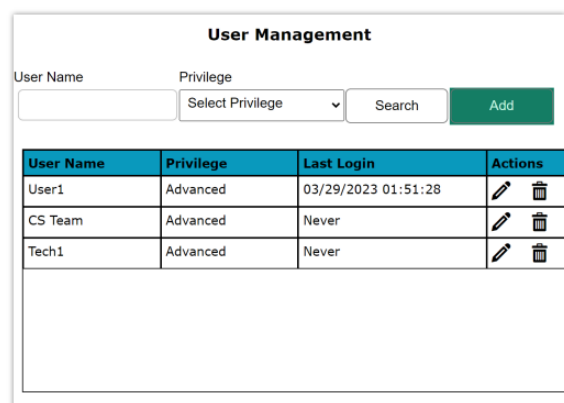
**1** Select **Site Settings**.



**2** 1. Select Security.  
2. Add Well Name.  
3. Click **User Management**.



**3** 1. Scroll the cursor to 'Add'.  
2. Fill in the Username, Password, and Privilege information.  
**Note:** Password to be 8 characters containing letters and/or numbers.  
3. Press 'Add User'.



**4** 1. New user will appear in the list.  
2. Delete User1. Make sure that new user is added first. **Do not forget the password.**

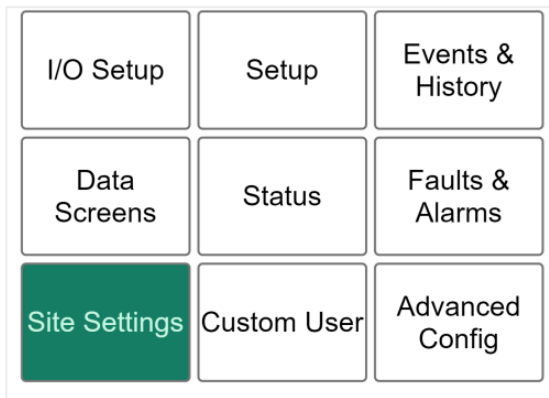


# Set Up Wi-Fi

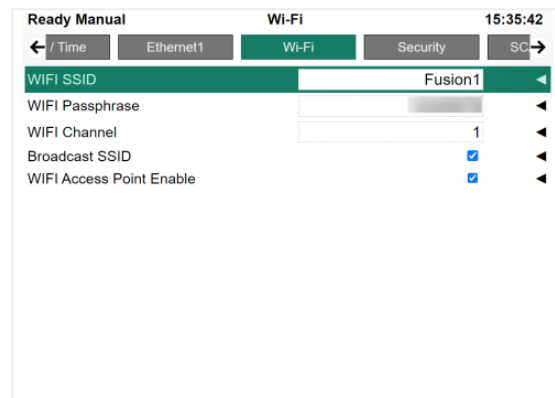
**NOTICE**

This system is equipped with a Wi-Fi access point that provides the ability to monitor data and configure settings via remote devices within the Wi-Fi range.

If the Wi-Fi functionality is enabled, the SSID and Wi-Fi password **MUST** be changed from default settings to ensure system security and prevent unauthorized access.



**1** Select **Site Settings**.

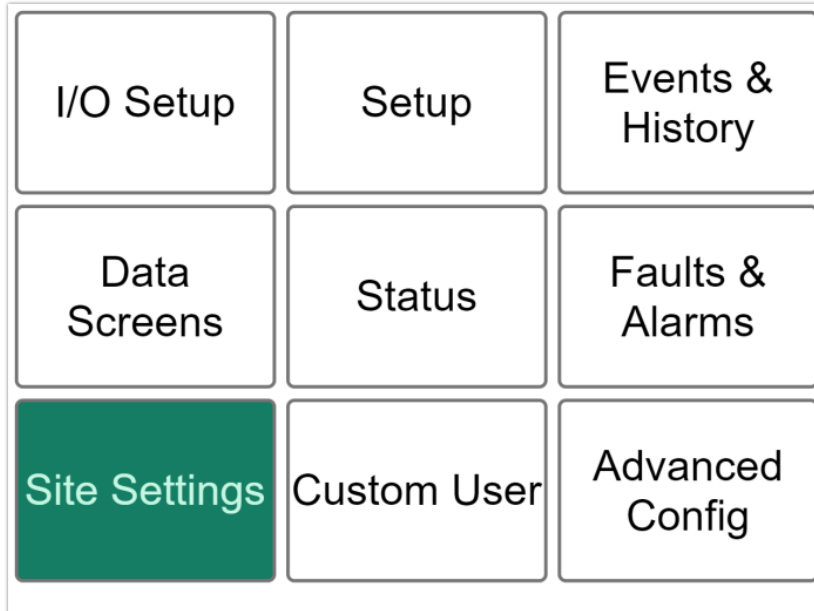


**2**

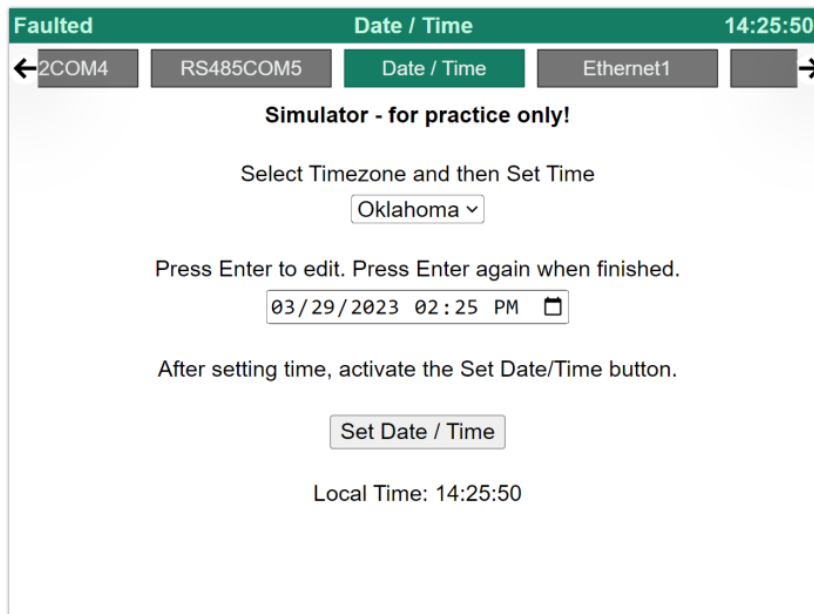
1. Select Wi-Fi tab.
2. Edit WIFI SSID.
3. Edit WIFI Passphrase.
4. Change WIFI Channel as needed.

**Note:** Passphrase length must be at least 8 characters.

# Set Up Time and Zone

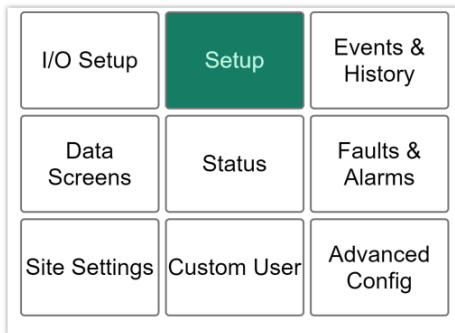


**1** Selected **Site Settings**.

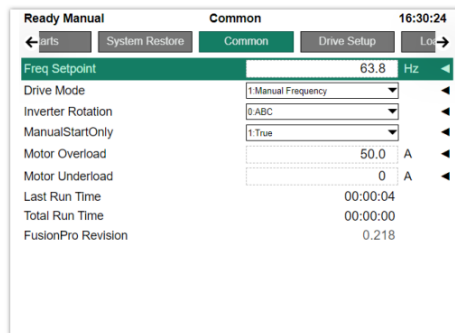


- 2** 1. Select Date / Time tab.
2. To set date and time, follow instructions on the screen.

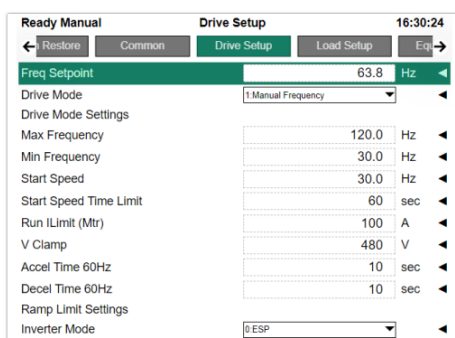
# Perform a Basic Set-Up



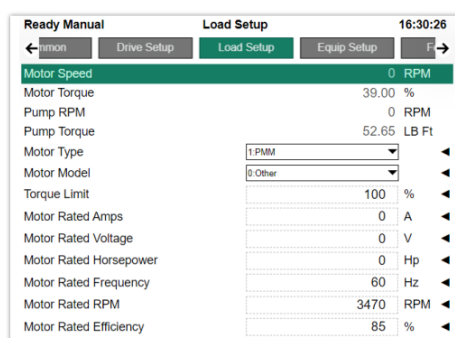
**1** Select **Setup**.



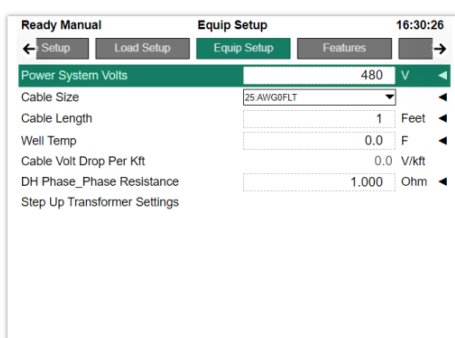
**2** 1. Select Common tab.  
2. Update parameters as necessary.



**3** 1. Select Drive Setup tab.  
2. Update parameters as necessary.



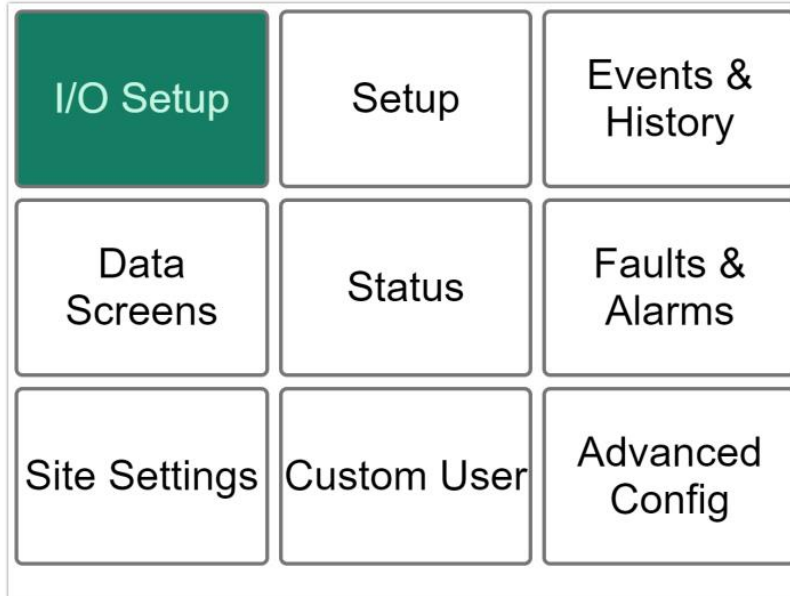
**4** 1. Select Load Setup tab.  
2. Add Torque Limit.  
3. Add Motor Rated Amps.  
4. Add Motor Mag Current.  
5. Add Motor Rated Voltage.  
6. Add Motor Rated Horsepower.  
7. Add Motor Rated RPM.



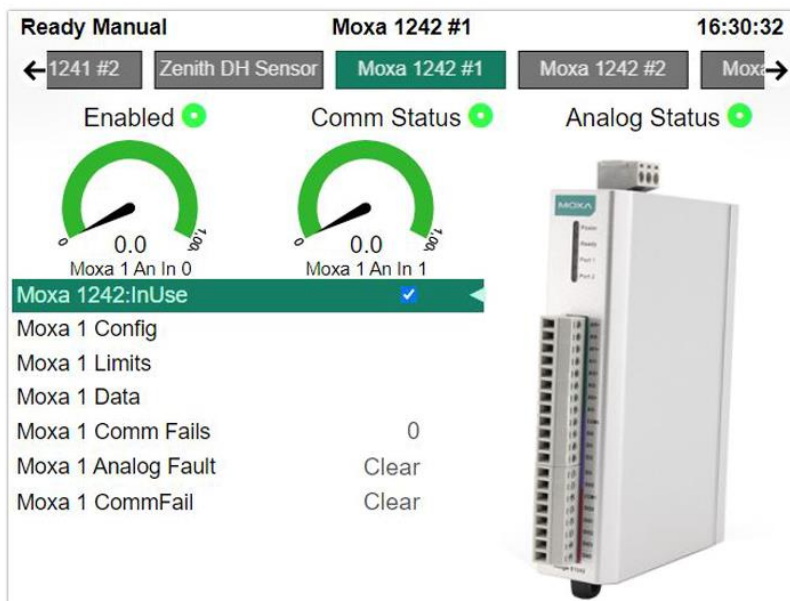
**5** 1. Select Equip Setup tab.  
2. Select Cable Size.  
3. Add Cable Length.  
4. Add Well Temp.  
5. Add Step Up Transformer parameters.

**Note:** Refer to the FusionPro™ System Controller Manual for detailed instructions on how to perform a basic set-up.

# Set-up I/O module

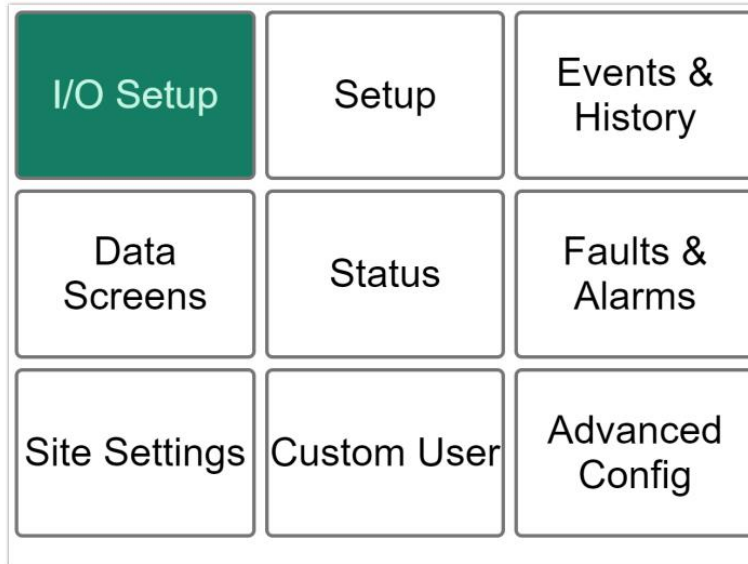


- 1 Select **I/O Setup**.

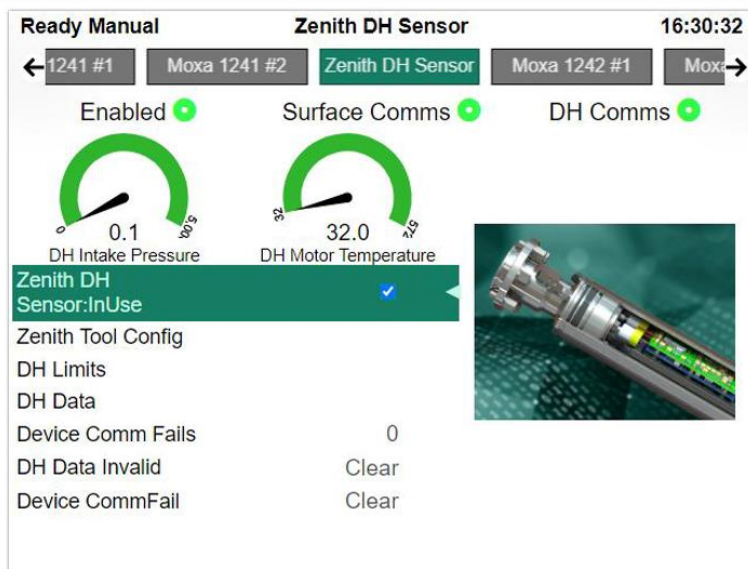


- 2 1. Make sure that 'Moxa 1242:InUse' parameter is checked.  
2. Make sure that Enabled, Comm Status, and Analog Status LEDs show green.

# Set-up a Zenith DH Sensor



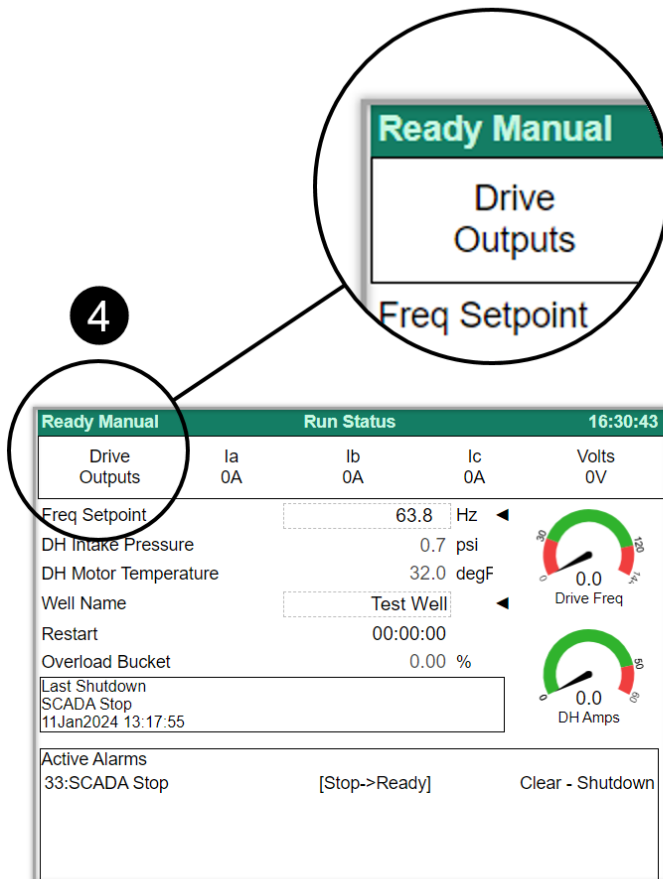
- 1 Select **I/O Setup**.



- 2
  1. Make sure that 'Zenith DH Sensor:InUse' parameter is checked.
  2. Make sure that Enabled, Surface Comms, and DH Comms LEDs show green.

**Note:** If setting up other than Zenith, refer to the FusionPro™ System Controller Manual for details.

# Make Sure the Drive is Ready to Start



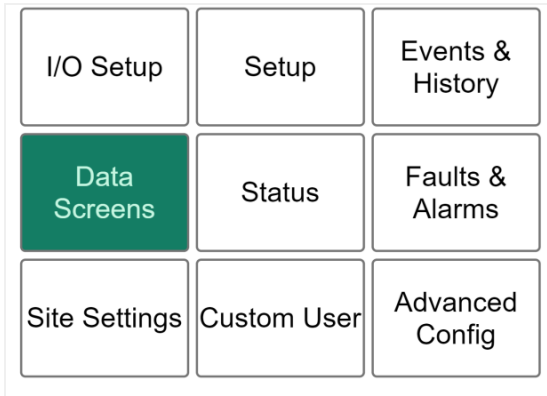
The screenshot shows the FusionPro control interface. At the top, a green status bar displays 'Ready Manual'. Below this, a 'Run Status' section contains several parameters: Drive Outputs (Ia, Ib, Ic, Volts), Freq Setpoint (63.8 Hz), DH Intake Pressure (0.7 psi), DH Motor Temperature (32.0 degF), Well Name (Test Well), Restart (00:00:00), and Overload Bucket (0.00 %). There are also two gauges for Drive Freq and DH Amps. At the bottom, an 'Active Alarms' section shows '33:SCADA Stop' with a '[Stop->Ready]' status and a 'Clear - Shutdown' button. A callout box with the number '4' points to the 'Ready Manual' status bar and the 'Freq Setpoint' field.

Before starting the drive, make sure:

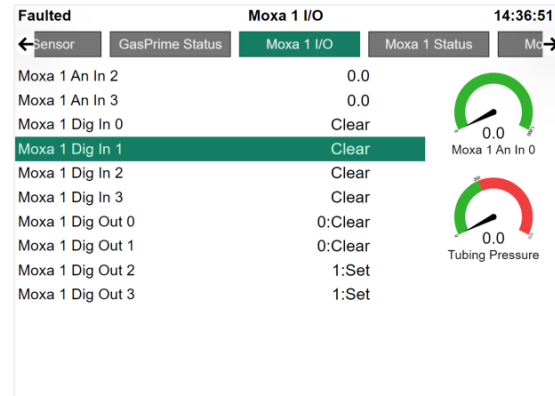
- 1 Drive Ground is connected.
- 2 All doors are locked.
- 3 Switch handle is in the Closed (ON) position.
- 4 Top status bar on the Run Status screen displays **Ready Manual**.

**Note:** Refer to the FusionPro™ System Controller Manual to clear any faults or for more advanced setup.

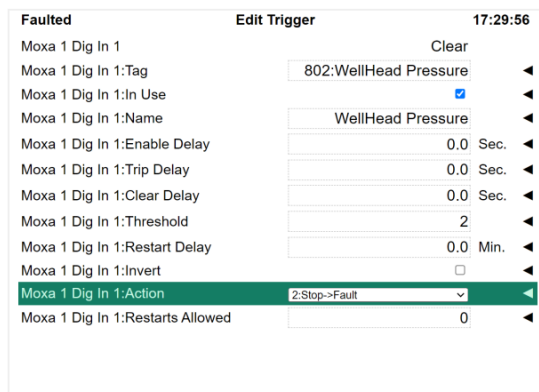
# Set-up a digital input to create a drive alarm



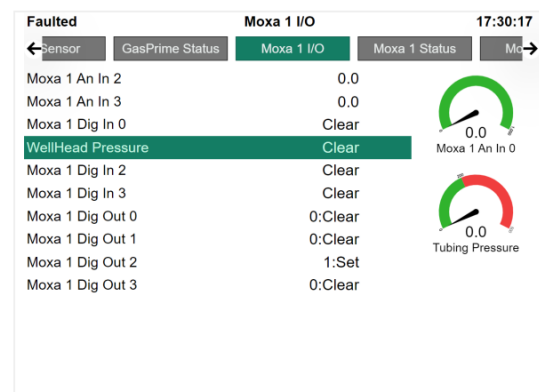
**1** Select **Data Screens**.



**2** 1. Select Moxa 1 I/O tab.  
2. Select Moxa 1 Dig In 1 parameter and press *Enter*.  
3. The screen that opens will allow complete configuration of this digital input.



**3** 1. Select the Name parameter and press *Enter*. Use the pop-up keyboard to delete the default name and add new name "WellHead Pressure".  
2. Select Action parameter and press *Enter*. Select Stop->Fault from the drop-down list.  
3. Edit the Enable Delay and Trip Delay parameters to add delays if needed.  
4. Make sure that the In Use parameter is checked to enable this digital input.



**4** This Moxa 1 Digital Input is now configured for use in the drive. When the status of the digital input changes, the display will show "Set". If the drive is running, it will stop on a WellHead Pressure alarm.

# Reference Information

Scan the below QR code to access the following FusionPro™ manuals:

- FusionPro™ Operations Manual (500031032)
- FusionPro™ System Controller Manual (500024500)

